

Rangkuman Korespondensi:

Judul: Optimizing Adjustable Parameters of Servo Controller by Using UniNeuro_HUDGA for Laser-Auto-Focus-Based Tracking System

Journal : IEEE Access (Volume: 5)

Page(s): 823 - 832

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Tanggal	Tema/ kegiatan
15-03-2016	Diskusi dengan rekan tentang persiapan pengiriman artikel ke IEEE
17-03-2016	Diskusi dengan supervisor tentang kemungkinan journal target
31-05-2016	Diskusi dengan supervisor tentang progress eksperimen untuk artikel berikutnya
17-10-2016	Diskusi dengan rekan partikel ke 3
25-10-2016	Diskusi dengan supervisor untuk menentukan IEEE Access sebagai target
14-12-2016	Diskusi dengan supervisor proses revisi untuk submit ke IEEE Access
07-01-2017	Submit ke IEEE access
11-01-2017	Accepted by IEEE access
12-01-2017	Proof article
20-01-2017	Proof article
24-01-2017	Published

Re: 3th paper Revised

From: Dony Hidayat (aljananku@yahoo.com)
To: tom.b0519@msa.hinet.net
Date: Tuesday, March 15, 2016, 07:57 PM GMT+7

Dear Mr. Chen

Okay, I will do my best.

Thank you very much

Dony Hidayat Al-Janan
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email :
u0215917@nkfust.edu.tw
aljanan@mail.unnes.ac.id
aljananku@gmail.com
aljananku@yahoo.com

On Tuesday, March 15, 2016 8:43 PM, 陳業鵬 <tom.b0519@msa.hinet.net> wrote:

Dear Dony,
I suggest you to re-organize your introduction section, at first glance, it seems not smooth.
Oral and too incosistent. It is not easy to read.

Best Wish,
Tom

從 Windows 10 的郵件傳送

寄件者: [Dony Hidayat](#)
傳送時間: 2016年3月14日 下午 04:59
收件者: [chen tom](#); [chen tom](#)
副本: [LIU my professor](#); [chang NKFUST LIU](#)
主旨: 3th paper Revised

Dear Mr. Chen

I send to you my 3th paper draft that we will discuss on Friday, 20160318, at the Donnute Caffee.

Regarding your email address : tomchen@ticp.com.tw , tom.b0519@msa.hinet.net or u9615919@nkfust.edu.tw, which one you choose for your author email?

Thank you very much Mr. Chen

Best Regards,

Dony Hidayat Al-Janan
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email :
u0215917@nkfust.edu.tw
aljanan@mail.unnes.ac.id
aljananku@gmail.com
aljananku@yahoo.com

Re: Journal for 3th paper

From: 劉東官 (tkliu@nkfust.edu.tw)

To: aljananku@yahoo.com

Date: Thursday, March 17, 2016, 12:47 PM GMT+7

Can it accept our paper soon? If the answer is OK, I am also OK.

-----Original message-----

From: Dony Hidayat <aljananku@yahoo.com>

To: 劉東官 <tkliu@nkfust.edu.tw>

Date: Thu, 17 Mar 2016 11:47:30

Subject: Re: Journal for 3th paper

Dear Prof. Liu

What do you think about this journal?

International Journal of Intelligent Computing and Cybernetics

ISSN : 1756-378X

Emerald | International Journal of Intelligent Computing and Cybernetics information

Emerald | International Journal of Intelligent Computing...Home > Emerald journals > International Journal of Intelligent Computing and Cybernetics Information International Journal of Intelligent Computing and Cybernetics...

View on www.emeraldgrouppub...

Preview by Yahoo

Thank you very much Prof. Liu

Best Regards,

Dony Hidayat Al-Janani

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email :

u0215917@nkfust.edu.twaljananku@mail.unnes.ac.id

aljananku@gmail.com

aljananku@yahoo.com

On Thursday, March 17, 2016 12:28 AM, 劉東官 <tkliu@nkfust.edu.tw> wrote:

Dear Dony: This paper can be only EI. Please choose an easy one which can accept our paper as soon as possible.
Best Wishes,

TK-----Original message-----From:Dony Hidayat<aljananku@yahoo.com>To:LIU my

professor<tkliu@nkfust.edu.tw>Date: Wed, 16 Mar 2016 15:22:51Subject: Journal for 3th paperDear Prof. Liu

My 2nd paper is submitted to Kybernetes yesterday.

for my 3th paper, I have been trying for searching the appropriate journals and got three journals but all are in SCI index, they are:

1. journal of supercomputing
2. Optimization Letters
3. Optimization

which journal you prefer to choose?

or maybe you have another choice?

I send to you the information regarding that three journals.

Now, I am preparing for other alternative paper; which I will try solve PCB hole problem (my paper 1 case) using HUDGA (Hybrid Uniform Design GA).

Thank you very much Prof. Liu

Best Regards,

Dony Hidayat Al-Janani Doctoral Student Program National Kaohsiung First University of Science and Technology, Taiwan No.1, University Rd., Yanchao Dist., Kaohsiung City 824, Taiwan (R.O.C.) Phone. +886-981 083 584 (Taiwan); +62-818 456 109 (Indonesia) email :
u0215917@nkfust.edu.twaljanan@mail.unnes.ac.idaljananku@gmail.comaljananku@yahoo.com

Re: Fw: PID setting for LDS Progress

From: Dony Hidayat (aljananku@yahoo.com)
To: tkliu@nkfust.edu.tw
Date: Tuesday, May 31, 2016, 08:28 AM GMT+7

Dear Prof. Liu,

The journal is free.
I will discuss with Jim about his curriculum.
This day, I am writing paper in my dorm due to the internet connection.
Thank you Prof. Liu for your suggestion and correction.

Best regards,

Dony Hidayat Al-Janan
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email :
u0215917@nkfust.edu.tw
aljanan@mail.unnes.ac.id
aljananku@gmail.com
aljananku@yahoo.com

On Tuesday, May 31, 2016 12:23 AM, 劉東官 <tkliu@nkfust.edu.tw> wrote:

Dear Dony:

How much is publication fee? Is it free?

I agree that you invite Mr. Jim as the second author. Jim's information should be "Jim^{1,3}" and "3" is Contrel Technology Co. LTD.(<http://www.contrel.com.tw/>),
Withe Best Wishes,

Tung-Kuan

-----Original message-----

From: Dony Hidayat<aljananku@yahoo.com>
To: 劉東官<tkliu@nkfust.edu.tw>
Date: Mon, 30 May 2016 23:09:13
Subject: Re: Fw: PID setting for LDS Progress

Dear Prof. Liu

This evening, Jim already finished total confirmation; then the result proofs that we already obtained better result than trial and error method (it shown in 'confirmation data_20160530-again speed 200_add20160530.xlsx' page 'TOTAL confirmation').

Regarding that progress, tomorrow I will focus to finished my fourth paper and submit it

to <http://www.springer.com/computer/theoretical+computer+science/journal/453>,

based on the information, in most cases, the decision is made in less than 4 months.

then, if you do not mind, I will invite Jim as the second author. I send to you the draft, and need your suggestion.

Thank you very much Prof. Liu

Best Regards,

Dony Hidayat Al-Janani

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email :

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aljanani@mail.unnes.ac.id

aljananku@gmail.com

aljananku@yahoo.com

On Wednesday, May 25, 2016 5:57 PM, 劉東官 <tkliu@nkfust.edu.tw> wrote:

Thank you very much.

-----Original message-----

From: Dony Hidayat <aljananku@yahoo.com>

To: LIU my professor <tkliu@nkfust.edu.tw>

Date: Wed, 25 May 2016 17:27:03

Subject: Fw: PID setting for LDS Progress

Dear Prof. Liu

I already fix the link of confirmation data_20160515

I use 2 objectives, max error and error area (for checking stability performance); thus we got the better result than the trial-error method for all both objectives.

Thank you very much Prof. Liu

Best Regards,

Dony Hidayat Al-Janani
Doctoral Student Program
National Kaohsiung First University of Science and
Technology, Taiwan
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email :
u0215917@nkfust.edu.tw
aljanan@mail.unnes.ac.id
aljananku@gmail.com
aljananku@yahoo.com

On Wednesday, May 25, 2016 10:38 AM, Dony Hidayat <aljananku@yahoo.com> wrote:

Dear Prof. Liu

We already got the better result of PID setting, as the attachment file.
But, because the UD result is changed comparing the previous result (confirmation data_20160509.xlsx), so than Jim will re-confirmation within UD setting (confirmation data_20160515, setting 1 to 6).
Hope, my 4th paper will be submit on the end of this month.
Meanwhile, Due to lack of the internet connection in our lab, sometimes I prefer do my job in my dorm.

Thank you very much Prof. Liu

Best Regards,

Dony Hidayat Al-Janani
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email :
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aljanan@mail.unnes.ac.id
aljananku@gmail.com
aljananku@yahoo.com

Re: IEEE ACCESS

From: Dony Hidayat (aljananku@yahoo.com)
To: hpowen@nkfust.edu.tw
Date: Monday, October 17, 2016, 08:53 AM GMT+7

Dear Prof. Hsueh

Okay, Prof. Hsueh.
I will check for it.
Thank you very much.

Best Regards,

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aljananku@gmail.com
aljananku@yahoo.com

On Sunday, October 16, 2016 11:58 PM, 薛博文 <hpowen@nkfust.edu.tw> wrote:

Hi Dony

First, I have modified the article "Optimizing.....for Laser-Auto-Focus-Based Tracking System".
We can check it again with Prof. Liu.

Then, a new figure is drawn to utilize in the paper after figure 1. You can add this figure with editing some words.

Sincerely

Power

-----Original message-----

From: Dony Hidayat<aljananku@yahoo.com>
To: 薛博文 <hpowen@nkfust.edu.tw>

Date: Sat, 15 Oct 2016 00:06:03

Subject: Re: IEEE ACCESS

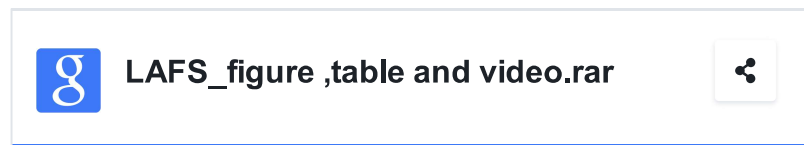
Dear Prof. Hsueh,

Here I send to you the latest revision.

I use term 'laser auto focus system that used for auto-tracking the profile'.

the figure and table can be download in:

[LAFS_figure ,table and video.rar](#)



thank you very much.

Best regards,

Dony Hidayat Al-Janani

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email :

u0215917@nkfust.edu.tw

aljanan@mail.unnes.ac.id

aljananku@gmail.com

aljananku@yahoo.com

On Tuesday, October 11, 2016 12:23 AM, 薛博文 <hpowen@nkfust.edu.tw> wrote:

Hi Dony.

I try to use "adjustable parameters and tunable parameters for the servo controller.

Since the adjustable parameters are appeared in several literature, we can used the format to describe the servo controller.

The attachment is the revised version. Please refer.

Sincerely

Power



Re: IEEE Access Candidate

From: Dony Hidayat (aljananku@yahoo.com)
To: tkliu@nkfust.edu.tw; hpowen@nkfust.edu.tw
Date: Tuesday, October 25, 2016, 09:44 AM GMT+7

Dear Prof. Liu and Prof. Hsueh,

I send to you the latest revised of LDS paper.
The table, figure and movie can be download in this link.
<https://drive.google.com/open?id=0B7wDO8k2LTvubFhmamo5SmhVaTg>

Thank you for your suggestion.

Best Regards,

Dony Hidayat Al-Janan
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email :
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aljananku@gmail.com
aljananku@yahoo.com

On Monday, October 17, 2016 12:07 PM, 劉東官 <tkliu@nkfust.edu.tw> wrote:

Table 1, Controller Input Boundary ==> Controller Parameter Boundary

-----Original message-----

From: Dony Hidayat <aljananku@yahoo.com>

To: 劉東官 <tkliu@nkfust.edu.tw>, 薛博文 <hpowen@nkfust.edu.tw>

Date: Mon, 17 Oct 2016 11:46:44

Subject: IEEE Access Candidate

Dear Prof. Liu and Prof. Hsueh,

I send to you the latest revision of the third paper candidate.
The figure and table can be downloaded in

<https://drive.google.com/open?id=0B7wDO8k2LTvuSnhnUWZHY1NISU0>

Thank you very much for your suggestion.

Best Regards,

Dony Hidayat Al-Janani
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aljanani@mail.unnes.ac.id
aljananku@gmail.com
aljananku@yahoo.com



UniNeuroHUDGA_Manuscript_powen_20161024.docx
123.3kB

Paper 2 revision

From: Dony Hidayat (aljananku@yahoo.com)

To: tkliu@nkfust.edu.tw

Date: Wednesday, December 14, 2016, 03:27 PM GMT+7

Dear Prof. Liu,

I send to you the revision paper that we will re submit to IEEE ACCESS. Principally, Prof. Hsueh already agree, and he will do a part of revision based on your comment. According the response from associate editor, we got second chance therefore we need to re-submit as soon. Now, we already take 2 weeks for revision.

The file can be download in:

<https://drive.google.com/open?id=0B7wDO8k2LTvuUzZCZnNqS1dzVGc>

For my fourth paper, I already use your idea for using uniform design in the Neuro, but, when I confirmed the result with DIP, the result is not sufficient. Now, I am trying for modifying the NN structure. Thank you very much Prof. Liu

Dony Hidayat Al-Janan

Doctoral Student Program

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email :

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aljanan@mail.unnes.ac.id

aljananku@gmail.com

aljananku@yahoo.com

Your Article has been received by IEEE (ACCESS2650959)

From: wmsprod@ieee.org

To: u0215917@nkfust.edu.tw; aljananku@yahoo.com

Date: Saturday, January 7, 2017, 11:23 PM GMT+7

Dear Mr. Dony Al-Janani

IEEE Publishing Operations received your article, "Optimizing Adjustable Parameters of Servo Controller by Using UniNeuro-HUDGA for Laser-Auto-Focus-Based Tracking System," DOI (identifier) 10.1109/ACCESS.2017.2650959, for publication in IEEE Access. IEEE will be contacting you periodically with updates on the progress of your article through the production process.

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The identification information we received with your article is as follows:

1) Dony, 2) Al-Janani, 3) u0215917@nkfust.edu.tw

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From: xea@ieee.org

To: u0215917@nkfust.edu.tw; aljananku@yahoo.com

Cc: p.j.kempf@ieee.org; xea@ieee.org

Date: Saturday, January 7, 2017, 11:24 PM GMT+7

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"Optimizing Adjustable Parameters of Servo Controller by Using UniNeuro-HUDGA for Laser-Auto-Focus-Based Tracking System"

10.1109/ACCESS.2017.2650959

Access-2016-02942

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Patrick J Kempf, Journals Coordinator

p.j.kempf@ieee.org

Congratulations! Your article has been published as a preprint

From: wmsprod@ieee.org

To: aljananku@yahoo.com; u0215917@nkfust.edu.tw

Date: Wednesday, January 11, 2017, 07:31 AM GMT+7

Dear Mr. Dony Al-Janani

This is to notify you that the following article, "Optimizing Adjustable Parameters of Servo Controller by Using UniNeuro-HUDGA for Laser-Auto-Focus-Based Tracking System," is available under the "Early Access" area on IEEEExplore, where the PDF of your author-submitted, peer-reviewed, and accepted manuscript is available for download. This article has been accepted for publication in a future issue of this journal, but has not been edited and content may change prior to final publication. It may be cited as an article in a future issue by its Digital Object Identifier. To view your Preprint article, please visit the journal homepage (listed below) on IEEEExplore and select the "Early Access" tab.

This paper appears in: IEEE Access

Issue Date: <not found>

Volume: <not found> Issue: <not found>

On page(s): 0

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Digital Object Identifier: 10.1109/ACCESS.2017.2650959

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From: p.j.kempf@ieee.org

To: u0215917@nkfust.edu.tw; aljananku@yahoo.com

Date: Thursday, January 12, 2017, 02:45 AM GMT+7

Dear Mr. Dony Al-Janani

The proof for your article, Optimizing Adjustable Parameters of Servo Controller by Using UniNeuro-HUDGA for Laser-Auto-Focus-Based Tracking System, is ready for your review. You may access your proof via the IEEE Author Gateway by following the steps below. Kindly log in to the website upon receipt of this message so that we may expedite the publication process. Please upload your comments and corrections through the Author Gateway by 12 January 2017.

Please see the following instructions to retrieve your proof:

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3. Use your IEEE Web Account User name and Password to Login.
4. Click on the "Continue" button at the bottom of the Login box.
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To upload your proof click on the upload proof button in the Author Gateway. This button appears in the Task Alert column of the Article Tracker indicating that the article is with you for review. During this time the upload proof button will also be available on the Article Status and Milestone page. Once you have reviewed your proof and made necessary changes, you can click on this button to upload your proof file.

When you click on the upload proof button, a separate window will open. You will be able to:

1. Browse and select your updated proof
2. Browse and select supplemental files
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When you have finished selecting your files and adding comments, please click on the upload proof button. All files will be uploaded and the status will change to In Final Production.

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Article title: Optimizing Adjustable Parameters of Servo Controller by Using UniNeuro-HUDGA for Laser-Auto-Focus-Based Tracking System

Journal acronym: ACCESS

Article DOI: 10.1109/ACCESS.2017.2650959

Manuscript Number: Access-2016-02942

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Thank you,

Patrick Kempf

Managing Editor

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From: p.j.kempf@ieee.org

To: u0215917@nkfust.edu.tw; aljananku@yahoo.com

Date: Friday, January 20, 2017, 03:16 AM GMT+7

Dear Mr. Dony Al-Janani

The proof for your article, Optimizing Adjustable Parameters of Servo Controller by Using UniNeuro-HUDGA for Laser-Auto-Focus-Based Tracking System, is ready for your review. You may access your proof via the IEEE Author Gateway by following the steps below. Kindly log in to the website upon receipt of this message so that we may expedite the publication process. Please upload your comments and corrections through the Author Gateway by 20 January 2017.

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3. Use your IEEE Web Account User name and Password to Login.
4. Click on the "Continue" button at the bottom of the Login box.
5. You should now see the Article Tracker IEEE Author Gateway page, with links to the Article Status page where you can download your proof and any associated documents under Resources.

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2. Browse and select supplemental files
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